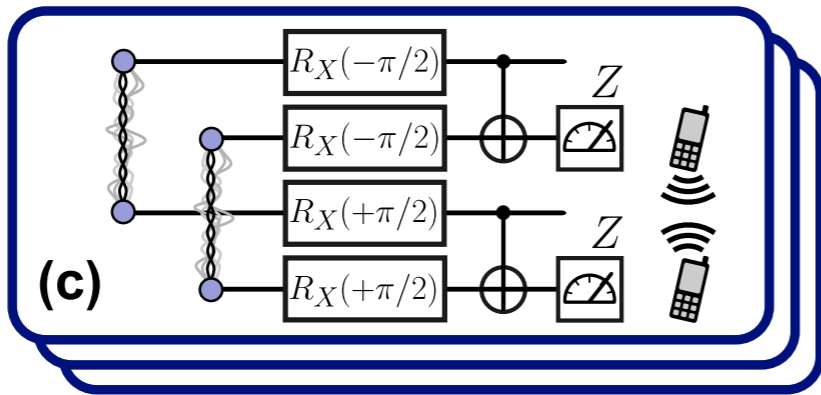
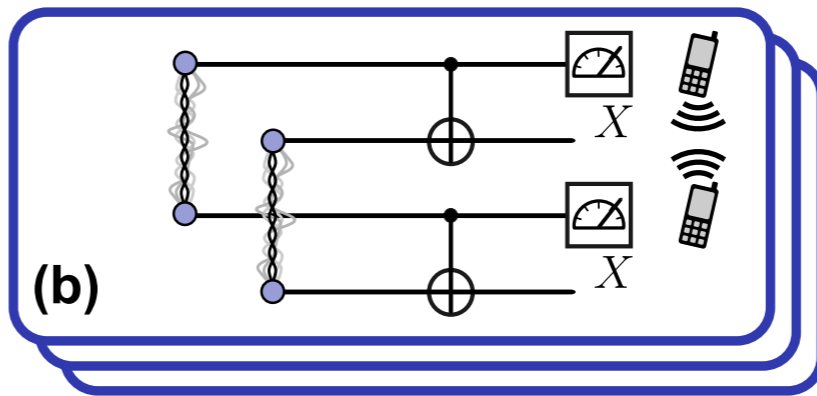
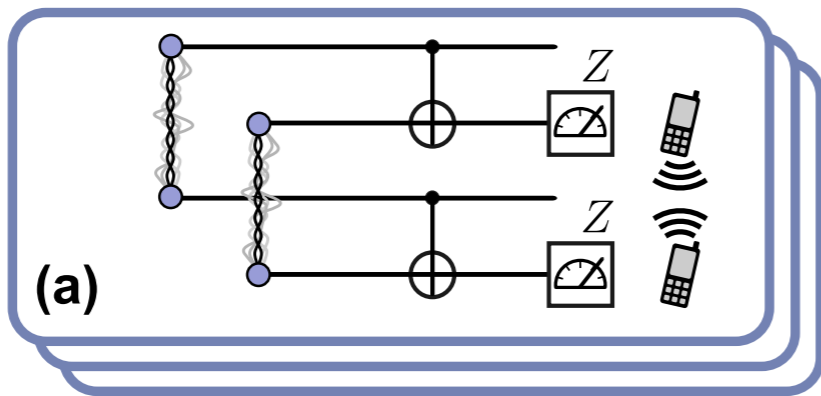
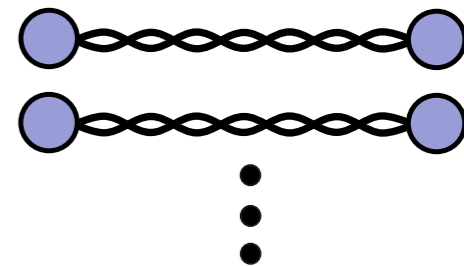


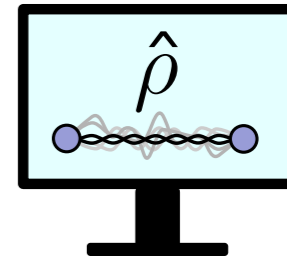
Noisy copies ρ



Measurement statistics $\{\hat{p}^{(i)}\}$



Distilled copies



State estimation