

SPECIAL RELATIVITY HOMEWORK – WEEK 1

In elementary physics, there are three main “axial vectors”, i.e. vectors that rely on the right-hand rule: angular velocity $\boldsymbol{\omega}$, angular momentum \mathbf{J} , and the magnetic field \mathbf{B} . As we discussed in the lecture, these quantities actually want to be bivectors, i.e. antisymmetric matrices. Let’s define the relationship between the axial vector and the corresponding bivector as:

$$\omega_{ij} = \epsilon_{ijk}\omega_k ; \quad \omega_i = \frac{1}{2}\epsilon_{ijk}\omega_{jk} . \quad (1)$$

Exercise 1. Rewrite the following equations using index notation and the bivectors ω_{ij} , J_{ij} and B_{ij} , without any ϵ_{ijk} ’s in the final result.

1. Rotational velocity: $\mathbf{v} = \boldsymbol{\omega} \times \mathbf{r}$.

2. Angular momentum: $\mathbf{J} = \mathbf{r} \times \mathbf{p}$.

3. Magnetic force: $\mathbf{F} = q\mathbf{v} \times \mathbf{B}$.

4. Maxwell’s equations:

$$\boldsymbol{\nabla} \cdot \mathbf{E} = \rho/\epsilon_0 ; \quad \boldsymbol{\nabla} \times \mathbf{E} = -\dot{\mathbf{B}} ; \quad \boldsymbol{\nabla} \cdot \mathbf{B} = 0 ; \quad \boldsymbol{\nabla} \times \mathbf{B} = \mu_0(\mathbf{j} + \epsilon_0\dot{\mathbf{E}}) . \quad (2)$$

Exercise 2. Do the same for the rotational inertia relation:

$$J_i = I_{ij}\omega_j , \quad (3)$$

where the symmetric matrix I_{ij} is the moment of inertia:

$$I_{ij} = \sum_{\text{particles}} m(r^2\delta_{ij} - r_i r_j) . \quad (4)$$

Some courage may be required.