The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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On the large N limit of the Schwinger-Dyson equation of tensor field theory

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Based on:

R. Pascalie, C. I. Pérez-Sánchez, and R. Wulkenhaar. arXiv:1706.07358.

R. Pascalie, C. I. Pérez-Sánchez, A. Tanasa and R. Wulkenhaar. arXiv:1810.09867.

01/11/2018

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Outline			

The model and the tools

- The model
- Boundary graph expansion of the free energy
- Ward-Takahashi Identity

2 Constraints on the scalings in N

- 2-point function
- 2k-point function with connected boundary graph
- 4-point function with disconnected boundary graph

3 The SDE in the large N limit

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- 2- and 4-point functions

4 Perspectives

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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I he model

Complex rank-3 bosonic tensor field theory: $U(N)^3$ -invariant "pillow" interactions

$$\begin{split} \mathcal{S}[\varphi,\bar{\varphi}] &= \mathcal{S}_{0}[\varphi,\bar{\varphi}] + \mathcal{S}_{\text{int}}[\varphi,\bar{\varphi}] \\ &= \sum_{\mathbf{x}} \bar{\varphi}^{\mathbf{x}} |\mathbf{x}|^{2} \varphi^{\mathbf{x}} + \lambda \sum_{c=1}^{3} \sum_{\mathbf{a},\mathbf{b}} \bar{\varphi}^{\mathbf{a}} \varphi^{\mathbf{b}_{\bar{c}} \mathbf{a}_{c}} \bar{\varphi}^{\mathbf{a}_{\bar{c}} b_{c}} \varphi^{\mathbf{a}}, \end{split}$$
(1)

with
$$\mathbf{x} = (x_1, x_2, x_3) \in \{\frac{1}{N}, \frac{2}{N}, \dots, 1\}^3$$
, $|\mathbf{x}|^2 = x_1^2 + x_2^2 + x_3^2$, $\lambda = N^{\delta} \tilde{\lambda}$,
 $\mathbf{a}_{\hat{c}} b_c = (a_1, \dots, a_{c-1}, b_c, a_{c+1}, \dots, a_D)$ for *D*-tuple.

The kinetic term represents the discrete Laplacian in the Fourier transformed space of the tensor index space.

The generating functional of the model writes:

$$Z[J,\bar{J}] = \int \mathcal{D}\varphi \mathcal{D}\bar{\varphi} \exp\left(-N^{\gamma} \mathcal{S}[\varphi,\bar{\varphi}] + N^{\beta} \sum_{\mathbf{x}} (\bar{J}_{\mathbf{x}} \varphi^{\mathbf{x}} + J_{\mathbf{x}} \bar{\varphi}^{\mathbf{x}})\right). \quad (2)$$

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Boundary graph			



Figure: Two connected Feynman graphs and the associated boundary graphs. In the figure a) the boundary graph V_1 is connected and $\mathbb{J}(V_1)(\mathbf{x}, \mathbf{y}) = J_x J_y \overline{J}_{x_1 y_2 y_3} \overline{J}_{y_1 x_2 x_3}$. In fig. b) the boundary graph m|m is disconnected and $\mathbb{J}(\mathbf{m}|\mathbf{m})(\mathbf{x}, \mathbf{y}) = J_x J_y \overline{J}_x \overline{J}_y$.

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Free energy			

The free energy is written as an expansion over boundary graphs:

$$W[J,\bar{J}] = \sum_{k=1}^{\infty} \sum_{\substack{\mathcal{B} \in \partial_{S_{int}} \\ V(\mathcal{B}) = 2k}} \sum_{\mathbf{X}} \frac{N^{\alpha(\mathcal{B})}}{|\operatorname{Aut}(\mathcal{B})|} G_{\mathcal{B}}^{(2k)}(\mathbf{X}) \cdot \mathbb{J}(\mathcal{B})(\mathbf{X}),$$
(3)

where $\partial_{S_{int}}$ is the set of boundary graphs, $V(\mathcal{B})$ is the number of vertices of \mathcal{B} , $\operatorname{Aut}(\mathcal{B})$ is the symmetry group of the graph \mathcal{B} , $\mathbf{X} = (\mathbf{x}^1, \dots, \mathbf{x}^k) \in \{\frac{1}{N}, \frac{2}{N}, \dots, 1\}^{3k}$, and $\mathbb{J}(\mathcal{B})(\mathbf{X}) = J_{\mathbf{x}^1} \dots J_{\mathbf{x}^k} \overline{J_{\mathbf{p}^1}} \dots \overline{J_{\mathbf{p}^k}}$. Where $\mathbf{p}^i = \mathbf{p}^i(\mathbf{X}) \in \{\frac{1}{N}, \frac{2}{N}, \dots, 1\}^3$ is a momentum triplet determined by the boundary graph \mathcal{B} .

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Green functions	5		

A 2k-point function with a boundary graph \mathcal{B} is taken to be

$$G_{\mathcal{B}}^{(2k)}(\mathbf{X}) = \left. \frac{\mathbf{N}^{-\alpha(\mathcal{B})}}{Z_0} \prod_{i=1}^k \left(\frac{\delta}{\delta \bar{J}_{\mathbf{p}^i}} \frac{\delta}{\delta J_{\mathbf{x}^i}} \right) W[J, \bar{J}] \right|_{J=\bar{J}=0} , \qquad (4)$$

where for all $c \in \{1,2,3\}$ and $(i,j) \in \{1,\ldots,k\}^2$, $x_c^i \neq x_c^j$.

The coefficient $\alpha(\mathcal{B})$ does not depend on the choice of colouring. For example, for the three pillow graphs $\alpha(V_1) = \alpha(V_2) = \alpha(V_3)$.

The model and the tools ○○○○●○	Constraints on the scalings in N 000000	The SDE in the large N limit	Perspectives
Ward-Takahashi	i Identity		

The WTI for rank-D tensor field theory writes:

$$\sum_{\mathbf{q}_{\hat{s}}} \frac{\delta \operatorname{Z}[J, \bar{J}]}{\delta J_{\mathbf{q}_{\hat{s}}m_{a}} \delta \bar{J}_{\mathbf{q}_{\hat{s}}n_{a}}} - \delta_{m_{a}n_{a}} \operatorname{Y}_{m_{a}}^{(a)}[J, \bar{J}] \cdot \operatorname{Z}[J, \bar{J}]$$

$$= \frac{N^{3\beta-2\gamma}}{m_{a}^{2} - n_{a}^{2}} \sum_{\mathbf{q}_{\hat{s}}} \left(\bar{J}_{\mathbf{q}_{\hat{s}}m_{a}} \frac{\delta}{\delta \bar{J}_{\mathbf{q}_{\hat{s}}n_{a}}} - J_{\mathbf{q}_{\hat{s}}n_{a}} \frac{\delta}{\delta J_{\mathbf{q}_{\hat{s}}m_{a}}} \right) \operatorname{Z}[J, \bar{J}], \quad (5)$$

where $\mathbf{q}_{\hat{a}} = (q_1, \dots, q_{a-1}, q_{a+1}, \dots, q_D)$. The Y-term above is a functional given by

$$Y_{m_{a}}^{(a)}[J,\bar{J}] = \delta_{m_{a}n_{a}} \sum_{\mathbf{q}_{a}} \frac{\delta^{2} W[J,\bar{J}]}{\delta J_{q_{1}...q_{a-1}}m_{a}q_{a+1}...q_{D}} \delta \bar{J}_{q_{1}...q_{a-1}}n_{a}q_{a+1}...q_{D}}$$
$$= \sum_{\mathcal{B} \in \partial_{\mathcal{S}_{int}}} \sum_{\mathbf{X}} f_{a}(\mathbf{X}; m_{a}; \mathcal{B}) \cdot \mathbb{J}(\mathcal{B})(\mathbf{X}), \tag{6}$$

The model and the tools ○○○○○●	Constraints on the scalings in N 000000	The SDE in the large <i>N</i> limit	Perspectives
Y-term			
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Figure: Contributions to the term $f_1(\mathbf{x}; m_1; \mathbf{m})$ in the boundary graph expansion of $Y_{m_1}^{(1)}[J, \bar{J}]$.

$$f_{1}(\mathbf{x}; m_{1}; \mathbf{m}) = G_{1}^{(4)}(\mathbf{x}, m_{1}, x_{2}, x_{3}) + \sum_{q_{3}} G_{2}^{(4)}(\mathbf{x}; m_{1}, x_{2}, q_{3}) + \sum_{q_{2}} G_{3}^{(4)}(\mathbf{x}; m_{1}, q_{2}, x_{3}) + \sum_{q_{2}, q_{3}} G_{\mathbf{m}|\mathbf{m}}^{(4)}(\mathbf{x}, m_{1}, q_{2}, q_{3}).$$
(7)

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Constraining t	he scalings		

Aim: get from the SDE, a set of inequalities between the scaling coefficients α , β , γ and δ , such that:

- there is no divergent terms
- $\frac{1}{N} \sum \rightarrow \int$
- the higher point functions are decoupled

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Constraining t	he scalings		

Aim: get from the SDE, a set of inequalities between the scaling coefficients α , β , γ and δ , such that:

- there is no divergent terms
- $\frac{1}{N} \sum \rightarrow \int$
- the higher point functions are decoupled

The 2-point function explicitly writes

$$\begin{aligned}
\mathbf{G}^{(2)}(\mathbf{x}) &= \frac{N^{-\alpha}}{Z_0} \frac{\delta^2 \mathbf{Z}[J, \bar{J}]}{\delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} \bigg|_{J=\bar{J}=0} \\
&= \frac{N^{2\beta-\gamma-\alpha}}{|\mathbf{x}|^2} - \frac{N^{2\beta-\gamma-\alpha}}{Z_0} \frac{N^{\gamma}}{|\mathbf{x}|^2} \left(\bar{\varphi}^{\mathbf{x}} \frac{\partial \mathcal{S}_{\text{int}}}{\partial \bar{\varphi}^{\mathbf{x}}} \right) \left[\frac{1}{N^{2\beta-\gamma}} \frac{\delta}{\delta J}, \frac{1}{N^{2\beta-\gamma}} \frac{\delta}{\delta \bar{J}} \right] \mathbf{Z}[J, \bar{J}] \bigg|_{J, \bar{J}=0}
\end{aligned}$$
(8)

In order for the free propagator to be dominant in the large ${\it N}$ limit, one has:

$$\alpha = 2\beta - \gamma. \tag{9}$$

The model and the tools	Constraints on the scalings in N ○●○○○○	The SDE in the large N limit	Perspectives
2-point function	1		

$$\mathrm{G}^{(2)}(\boldsymbol{\mathsf{x}}) = \frac{1}{|\boldsymbol{\mathsf{x}}|^2}$$

(10)

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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2-point function	١		

$$\mathbf{G}^{(2)}(\mathbf{x}) = \frac{1}{|\mathbf{x}|^2} - \frac{2\tilde{\lambda}}{|\mathbf{x}|^2} \sum_{a=1}^3 \left(\frac{N^{3\gamma+2+\delta-4\beta}}{N^2} \sum_{\mathbf{q}_{\hat{a}}} \mathbf{G}^{(2)}(\mathbf{q}_{\hat{a}} x_a) \mathbf{G}^{(2)}(\mathbf{x}) \right)$$

(10)

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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2-point function	1		

$$\begin{split} \mathbf{G}^{(2)}(\mathbf{x}) &= \frac{1}{|\mathbf{x}|^2} - \frac{2\tilde{\lambda}}{|\mathbf{x}|^2} \sum_{a=1}^3 \left(\frac{N^{3\gamma+2+\delta-4\beta}}{N^2} \sum_{\mathbf{q}_{\hat{s}}} \mathbf{G}^{(2)}(\mathbf{q}_{\hat{s}} x_a) \mathbf{G}^{(2)}(\mathbf{x}) \right. \\ &+ \frac{N^{\alpha(V_1)}}{N^{8\beta-5\gamma-\delta}} \mathbf{G}_a^{(4)}(\mathbf{x}, \mathbf{x}) + \frac{N^{\alpha(m|m)+2}}{N^{8\beta-5\gamma-\delta}} \frac{1}{N^2} \sum_{\mathbf{q}_{\hat{s}}} \mathbf{G}_{m|m}^{(4)}(\mathbf{q}_{\hat{s}} x_a, \mathbf{x}) \\ &+ \frac{N^{\alpha(V_1)+1}}{N^{8\beta-5\gamma-\delta}} \frac{1}{N} \sum_{c \neq a} \sum_{q_b} \mathbf{G}_c^{(4)}(\mathbf{x}, \mathbf{x}_{\hat{b}} q_b) \end{split}$$

(10)

where $b \neq c$ and $b \neq a$.

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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2-point function			

$$G^{(2)}(\mathbf{x}) = \frac{1}{|\mathbf{x}|^{2}} - \frac{2\tilde{\lambda}}{|\mathbf{x}|^{2}} \sum_{a=1}^{3} \left(\frac{N^{3\gamma+2+\delta-4\beta}}{N^{2}} \sum_{\mathbf{q}_{a}} G^{(2)}(\mathbf{q}_{\hat{a}}x_{a}) G^{(2)}(\mathbf{x}) + \frac{N^{\alpha(V_{1})}}{N^{8\beta-5\gamma-\delta}} G_{a}^{(4)}(\mathbf{x},\mathbf{x}) + \frac{N^{\alpha(m|m)+2}}{N^{8\beta-5\gamma-\delta}} \frac{1}{N^{2}} \sum_{\mathbf{q}_{a}} G_{m|m}^{(4)}(\mathbf{q}_{\hat{a}}x_{a},\mathbf{x}) + \frac{N^{\alpha(V_{1})+1}}{N^{8\beta-5\gamma-\delta}} \frac{1}{N} \sum_{c\neq a} \sum_{q_{b}} G_{c}^{(4)}(\mathbf{x},\mathbf{x}_{\hat{b}}q_{b}) + \frac{1}{N} \sum_{q_{a}} \frac{N^{2\gamma+\delta+1-3\beta}}{x_{a}^{2}-q_{a}^{2}} \left(G^{(2)}(\mathbf{x}_{\hat{a}}q_{a}) - G^{(2)}(\mathbf{x}) \right) \right),$$
(10)

where $b \neq c$ and $b \neq a$.

The SDE for a 2k-point function with a connected boundary graph:

$$\mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) = -\frac{2\tilde{\lambda}}{|\mathbf{p}^{1}|^{2}} \sum_{a} \left\{ \frac{N^{3\gamma+2+\delta-4\beta}}{N^{2}} \sum_{\mathbf{q}_{\hat{a}}} \mathbf{G}^{(2)}(\mathbf{q}_{\hat{a}}\boldsymbol{p}_{a}^{1}) \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) \right\}$$

(11)

The SDE for a 2k-point function with a connected boundary graph:

$$\begin{split} \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) &= -\frac{2\tilde{\lambda}}{|\mathbf{p}^{1}|^{2}} \sum_{a} \left\{ \frac{N^{3\gamma+2+\delta-4\beta}}{N^{2}} \sum_{\mathbf{q}_{a}} \mathbf{G}^{(2)}(\mathbf{q}_{\hat{a}}p_{a}^{1}) \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) \right. \\ &\left. + \frac{N^{4\gamma+\delta-6\beta}}{N^{\alpha(\mathcal{B})}} \mathbf{\hat{f}}_{a}\left(\mathbf{X}; p_{a}^{1}; \mathcal{B}\right) \right] \end{split}$$

(11)

The SDE for a 2k-point function with a connected boundary graph:

$$\begin{split} \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) &= -\frac{2\tilde{\lambda}}{|\mathbf{p}^{1}|^{2}} \sum_{a} \left\{ \frac{N^{3\gamma+2+\delta-4\beta}}{N^{2}} \sum_{\mathbf{q}_{\hat{a}}} \mathbf{G}^{(2)}(\mathbf{q}_{\hat{a}}\boldsymbol{p}_{a}^{1}) \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) \right. \\ &+ \frac{N^{4\gamma+\delta-6\beta}}{N^{\alpha(\mathcal{B})}} \mathfrak{f}_{a}\left(\mathbf{X}; \boldsymbol{p}_{a}^{1}; \mathcal{B}\right) + \frac{1}{N} \sum_{b_{a}} \frac{N^{2\gamma+\delta+1-3\beta}}{b_{a}^{2} - (x_{a}^{\gamma})^{2}} \left(\mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}) - \mathbf{G}_{\mathcal{B}}^{(2k)}(\mathbf{X}|_{x_{a}^{\gamma} \to b_{a}}) \right) \end{split}$$

(11)

The model and the tools constraints on the scalings in N The SDE in the large N limit constraints on the scalings in N constraints on the scaling in N constraints on the s

The SDE for a 2k-point function with a connected boundary graph:

$$G_{\mathcal{B}}^{(2k)}(\mathbf{X}) = -\frac{2\tilde{\lambda}}{|\mathbf{p}^{1}|^{2}} \sum_{a} \left\{ \frac{N^{3\gamma+2+\delta-4\beta}}{N^{2}} \sum_{\mathbf{q}_{a}} G^{(2)}(\mathbf{q}_{a}\rho_{a}^{1}) G_{\mathcal{B}}^{(2k)}(\mathbf{X}) + \frac{N^{4\gamma+\delta-6\beta}}{N^{\alpha(\mathcal{B})}} \mathfrak{f}_{a}\left(\mathbf{X}; \rho_{a}^{1}; \mathcal{B}\right) + \frac{1}{N} \sum_{b_{a}} \frac{N^{2\gamma+\delta+1-3\beta}}{b_{a}^{2} - (x_{a}^{\gamma})^{2}} \left(G_{\mathcal{B}}^{(2k)}(\mathbf{X}) - G_{\mathcal{B}}^{(2k)}(\mathbf{X}|_{x_{a}^{\gamma} \to b_{a}}) \right) + \frac{N^{2\gamma+\delta-3\beta}}{N^{\alpha(\mathcal{B})}} \sum_{\rho=2}^{k} \frac{1}{(\rho_{a}^{\rho})^{2} - (\rho_{a}^{1})^{2}} \frac{1}{\mathbb{Z}_{0}} \left[\frac{\partial \mathbb{Z}[J, \bar{J}]}{\partial \zeta_{a}(\mathcal{B}; 1, \rho)}(\mathbf{X}) - \frac{\partial \mathbb{Z}[J, \bar{J}]}{\partial \zeta_{a}(\mathcal{B}; 1, \rho)}(\mathbf{X}|_{x_{a}^{\gamma} \to \rho_{a}^{\rho}}) \right] \right\}$$
(11)

where \mathbf{x}^{γ} corresponds to the only white vertex such that $x_a^{\gamma} = s_a$ and $\zeta_a(\mathcal{B}; 1, \rho)$ is the graph obtained by swapping the a-coloured lines between \mathbf{p}^1 and \mathbf{p}^{ρ} .

The model and the tools	Constraints on the scalings in N ○○○●○○	The SDE in the large <i>N</i> limit 00	Perspectives
Swapping 1			



Figure: This figure shows the result of a swapping of the *a*-coloured lines between **s** and **p**^{ρ} in a graph \mathcal{B} . For $\mathbf{s} = \mathbf{p}^1$, it corresponds to the graph $\zeta_a(\mathcal{B}; 1, \rho)$. The white vertex \mathbf{x}^{γ} corresponds to the only white vertex such that $x_a^{\gamma} = s_a$, similarly $\mathbf{x}^{\kappa(\rho)}$ corresponds to the only white vertex such that $x_a^{\kappa(\rho)} = p_a^{\rho}$.

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Swanning 2			





Figure: The result of the swapping of the three different colours starting from the pillow graph V_1 . For the colours 2 and resp. 3, the swapping gives the graphs V_3 and resp. V_2 ; for colour 1, the swapping gives the disconnected graph m|m.

 The model and the tools
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 4-point function with disconnected boundary graph

The 4-point function with a disconnected boundary graph writes

$$G_{m|m}^{(4)}(\mathbf{x}, \mathbf{y}) = \frac{1}{N^{\alpha(m|m)}} \left. \frac{\delta^4 W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} \right|_{J=\bar{J}=0},$$
(12)

where

$$\frac{\delta^{4} \mathbf{W}[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} = -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{\delta^{2}}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{1}{\mathbf{Z}[J, \bar{J}]} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} \mathbf{Z}[J, \bar{J}] \right)$$

(13)

 The model and the tools
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 4-point function with disconnected boundary graph

The 4-point function with a disconnected boundary graph writes

$$G_{m|m}^{(4)}(\mathbf{x}, \mathbf{y}) = \frac{1}{N^{\alpha(m|m)}} \left. \frac{\delta^4 W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} \right|_{J=\bar{J}=0},$$
(12)

where

$$\begin{split} \frac{\delta^{4} \mathbf{W}[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} &= -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{\delta^{2}}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{1}{\mathbf{Z}[J, \bar{J}]} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta \mathcal{S}_{\mathrm{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} \mathbf{Z}[J, \bar{J}] \right) \\ &= -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{1}{\mathbf{Z}[J, \bar{J}]} \frac{\delta^{3}}{\delta J_{\mathbf{x}} \delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{\delta \mathcal{S}_{\mathrm{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} \mathbf{Z}[J, \bar{J}] \end{split}$$

(13)

 The model and the tools
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 4-point function
 with disconnected boundary graph

The 4-point function with a disconnected boundary graph writes

$$G_{m|m}^{(4)}(\mathbf{x}, \mathbf{y}) = \frac{1}{N^{\alpha(m|m)}} \left. \frac{\delta^4 W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} \right|_{J=\bar{J}=0},$$
(12)

where

$$\frac{\delta^{4} W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} = -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{\delta^{2}}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{1}{Z[J, \bar{J}]} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}] \right)$$

$$= -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{1}{Z[J, \bar{J}]} \frac{\delta^{3}}{\delta J_{\mathbf{x}} \delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}]$$

$$+ \frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{1}{Z^{2}[J, \bar{J}]} \frac{\delta^{2} Z[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}]. \quad (13)$$

(14)

The model and the tools Constraints on the scalings in N The SDE in the large N limit Perspectives <u>4-point function with disconnected bo</u>undary graph

The 4-point function with a disconnected boundary graph writes

$$G_{m|m}^{(4)}(\mathbf{x}, \mathbf{y}) = \frac{1}{N^{\alpha(m|m)}} \left. \frac{\delta^4 W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} \right|_{J=\bar{J}=0},$$
(12)

where

$$\frac{\delta^{4} W[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}} \delta \bar{J}_{\mathbf{x}} \delta J_{\mathbf{x}}} = -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{\delta^{2}}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{1}{Z[J, \bar{J}]} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}] \right)$$

$$= -\frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{1}{Z[J, \bar{J}]} \frac{\delta^{3}}{\delta J_{\mathbf{x}} \delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}]$$

$$+ \frac{N^{2\beta}}{|\mathbf{x}|^{2}} \frac{1}{Z^{2}[J, \bar{J}]} \frac{\delta^{2} Z[J, \bar{J}]}{\delta \bar{J}_{\mathbf{y}} \delta J_{\mathbf{y}}} \frac{\delta}{\delta J_{\mathbf{x}}} \left(\frac{\delta S_{\text{int}}}{\delta \bar{\varphi}^{\mathbf{x}}} \right)^{\partial} Z[J, \bar{J}]. \quad (13)$$

The two produces "disconnected" term which must cancel each other. This gives the constraint

$$2\beta = \gamma. \tag{14}$$

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Large N limit			

$$S[\varphi,\bar{\varphi}] = \sum_{\mathbf{x}} \bar{\varphi}^{\mathbf{x}} |\mathbf{x}|^2 \varphi^{\mathbf{x}} + \frac{\tilde{\lambda}}{N^2} \sum_{c=1}^{3} \sum_{\mathbf{a},\mathbf{b}} \bar{\varphi}^{\mathbf{a}} \varphi^{\mathbf{b}_{\bar{c}} a_c} \bar{\varphi}^{\mathbf{a}_{\bar{c}} b_c} \varphi^{\mathbf{a}}, \qquad (15)$$
$$G_{\mathcal{B}}^{(2k)}(\mathbf{X}) = \frac{N^{-\alpha(\mathcal{B})}}{Z_0} \prod_{i=1}^{k} \left(\frac{\delta}{\delta \bar{J}_{\mathbf{p}^i}} \frac{\delta}{\delta J_{\mathbf{x}^i}} \right) W[J,\bar{J}] \bigg|_{J=\bar{J}=0}, \qquad (16)$$

with the conjecture for the scaling

О

$$\alpha(\mathcal{B}) = 3 - B - 2g - 2k, \tag{17}$$

where 2k is the number of vertices of \mathcal{B} , B its number of connected components and g its genus. In the case of matrix model

$$\alpha(\mathcal{B}) = 2 - B - 2g,\tag{18}$$

see H. Grosse, R. Wulkenhaar, arXiv:1402.1041.

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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2- and 4-point functions			

$$G^{(2)}(\mathbf{x}) = \left(|\mathbf{x}|^2 + 2\tilde{\lambda} \sum_{a=1}^3 \int d\mathbf{q}_{\hat{a}} G^{(2)}(\mathbf{q}_{\hat{a}} x_a) \right)^{-1},$$
(19)
$$G_1^{(4)}(\mathbf{x}, \mathbf{y}) = -2\tilde{\lambda} G^{(2)}(x_1, y_2, y_3) G^{(2)}(\mathbf{y}) \frac{G^{(2)}(\mathbf{x}) - G^{(2)}(y_1, x_2, x_3)}{y_1^2 - x_1^2},$$
(20)

$$G_{m|m}^{(4)}(\mathbf{x}, \mathbf{y}) = -2\tilde{\lambda}G^{(2)}(\mathbf{x})\sum_{a=1}^{3} \left\{\sum_{c\neq a} \int dq_{b}G_{c}^{(4)}(x_{a}, q_{b}, y_{c}, \mathbf{y}) + \int d\mathbf{q}_{\hat{a}}G_{m|m}^{(4)}(\mathbf{q}_{\hat{a}}x_{a}, \mathbf{y})\right\},$$
(21)

where we used the SDE for the 2-point function to rewrite the SDE for the 4-point functions and where $d\mathbf{q}_{\hat{a}} = dq_b dq_c$ for $a \neq b, c$.

The model and the tools	Constraints on the scalings in N	The SDE in the large N limit	Perspectives
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Perspectives			

- Proving of the conjecture, using the SDE for disconnected boundary graphs.
- Solving the SDE in the large *N* limit, as it was done in arXiv:1807.02945 by E. Panzer and R. Wulkenhaar in the case of non-commutative quantum field theory.
- Implementing the methods for the study of SYK-like tensor models.

In the model with only the $1^{\rm st}$ pillow interaction, the renormalized SDE for the 2-point function

$$G^{(2)}(\mathbf{x}) = \left(1 + |\mathbf{x}|^2 + 2\lambda \int d\mathbf{q}_{\hat{1}} \left(G(\mathbf{q}_{\hat{c}} x_1) - \frac{1}{1 + |\mathbf{q}_{\hat{1}}|^2}\right)\right)^{-1}, \quad (22)$$

is solved by

$$G^{(2)}(\mathbf{x}) = \frac{1}{1+|\mathbf{x}|^2+g(x_1,z)},$$
 (23)

where

$$g(x_1, z) = zW\left(\frac{1}{z}e^{\frac{1+x_1^2}{z}}\right) - 1 - x_1^2,$$
 (24)

with $z = \frac{\pi}{2}\lambda$ and W(z) the Lambert function (which is defined by $z = W(ze^z)$).